

LBL POSITIONING AND COMMUNICATION SYSTEMS

PRODUCT INFORMATION GUIDE



EVOLOGICS S2C LBL UNDERWATER POSITIONING AND COMMUNICATION SYSTEMS

Evologics LBL systems bring the benefits of long baseline (LBL) acoustic positioning to offshore and maritime applications that demand highly accurate results. S2C R-series underwater acoustic modems that operate as transponders, deployed around the working area in an array of geo-referenced baseline nodes, allow to track and navigate mobile targets with highest accuracy that does not depend on the depth. Combining highly accurate LBL positioning with full benefits of an S2C technology communication link, an S2C LBL system delivers an excellent all-round performance ideal for application scenarios that demand space-, energy- and cost-saving solutions. Switching between positioning and communication modes is not necessary: positioning data is calculated simultaneously with acoustic transmissions. Both features complement each other in a fully integrated positioning and communication system that opens new possibilities for a wide range of subsea applications.

- \cdot Full compatibility use S2C R- and M -series modems as pingers or transponders
- Patented S2C (Sweep Spread Carrier) Technology spread spectrum technology based on extensive bionic studies
- \cdot LBL positioning with up to 1.5~cm accuracy
- Simultaneous LBL positioning and data transmissions, multiple target tracking
- "Silent" positioning mode: targets do not transmit beacon signals and self-position with broadcasts from baseline nodes
- Self-adaptive algorithms for reliable performance in adverse conditions, forward error correction and data compression
- Advanced communication protocol with several data delivery algorithms: send and receive large volumes of data with the highest bitrate possible in current conditions; send and receive short instant messages without interrupting the main data flow between devices
- · Addressing and networking: build relay chains and underwater networks with broadcasting capabilities
- · Low power consumption and additional power-saving options



APPLICATIONS

Positioning of offshore equipment

Track positions of offshore equipment during installation to ensure highly accurate placement at defined coordinates

Navigation of ROVs and AUVs

Simultaneously track positions of multiple ROVs or AUVs and control their missions with instant commands

Cartography

Locate underwater features with geo-referenced coordinates when used together with GPS or differential GPS

Sensor network tracking

Track drifts of moored sensors and detectors for accurate georeferencing of their measurements

Diver Tracking

Monitor positions of several divers and exchange information with them during the mission

MODULES AND OPTIONS

- AHRS (Attitude and Heading Reference System)
- GPS integration
- Integrated rechargeable battery
- Power-saving acoustic Wake-Up module
- Integrated data-logger
- Acoustic releases and floatation collars
- Short- mid- and long-range devices for shallow or deep water applications
- \cdot OEM versions available
- Compatible with S2C R modem and USBL solutions

SENSOR INTEGRATION

- ADCP: Acoustic Doppler Current Profiler
- SVP: Sound Velocity Profiler
- CTD: Conductivity, Temperature, Depth, Pressure sensors
- INS: Inertial Navigation System
- \cdot More options upon request

EVOLOGICS LBL COMMUNICATION AND POSITIONING SYSTEM: TYPICAL CONFIGURATION

MOBILE TRANSPONDER

MOBILE TRANSPONDER

Αυν

An LBL positioning system uses an array of sea-floor mounted baseline transponders: their exact locations are known, so they are used as reference points for determining target positions. Baseline transponders reply to acoustic interrogation signals from target-mounted transceivers with their own acoustic pulses, allowing a target transceiver to calculate its position by measuring the distance between itself and each transponder of the baseline array.

> BASELINE TRANSPONDER

BASELINE

TRANSPONDER

SINAPS POSITIONING SOFTWARE



Evologics SiNAPS positioning software is a clientserver application. SiNAPS server is installed on the navigation computer and interfaced with the vessel transceiver and other external instruments. SiNAPS server receives, processes and stores data from the transceiver and external instruments.

SiNAPS client is the web-based user interface of the positioning system. It displays real-time information about the positions of the vessel and the targets, provides access to data management tools and system configuration settings. The UI can be opened in most current web-browsers on multiple devices in the local computer network at once.

Baseline transponders are either mounted in sea-floor stands or equipped with acoustic release mechanisms and flotation collars for easier recovery to the surface. They are deployed around the work site and carefully calibrated prior to LBL system operation. Target transceivers are mounted on positioning targets, for example, on autonomous underwater vehicles (AUVs), remotely operated vehicles (ROVs) etc., and use acoustic signals to determine distances to baseline nodes.

BASELINE TRANSPONDER

A GPS receiver is installed on the vessel for accurate calibration of the baseline transponder array after its deployment. During calibration, the vessel moves above the deployed baseline transponders to accurately determine their location. Coupled with a vessel transceiver, the GPS receiver provides the baseline nodes' positions in real-world coordinates.

Third-party or built-in AHRS sensor (Attitude and Heading Reference System) provides information about the vessel's orientation during calibration to eliminate positioning errors. The navigation computer is installed on the vessel, interfaced with the vessel transceiver and other external instruments and connected to the local computer network. Evologics positioning software, the SiNAPS, and the Transponder communication utility, a web-based tool to monitor and control the baseline transponders, are accessible from the navigation computer to configure, control and monitor the mission.

SPECIFICATIONS AND CONFIGURATION OPTIONS

The LBL Positioning System uses S2C R-modems in baseline transponder configuration. Standard R-, M- and T-Series modems can be configured as target transceivers.

| | 0 1/1 | | | 0 | . , | | 0 | 0 | | | | | | | |
|--------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------|----------------------------------|----------------------------------|----------------------------------------------------------------|----------------------------------------------------------------|----------------------------------------------------------------|-----------------------------------------|--------------------------------------|----------------------------------------------------|-------------------------------------------|------------------------------------------|--------------------------------------------------|
| | | | R 48/78 | R 42/65 | R 18/34 | R 18/34H | R 15/27 | R 12/24 | R 7/17 | R 7/17D | R 7/17W | M 48/78 | M 42/65 | M 18/34 | M HS |
| GENERAL | OPERATING DEPTH | Delrin | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m | 200 m |
| | | Aluminium Alloy | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | | not av | ailable | |
| | | Stainless Steel | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m | 2000 m |
| | Titanium | | 2000 m | 2000 m | 2000 m | 2000 m | 6000 m | 6000 m | 6000 m | 10000 m upon request | 6000 m | | not av | ailable | |
| | OPERATING RANGE | | 1000 m | 1000 m | 3500 m | 3000 m | 6000 m | 6000 m | 8000 m | 10000 m | 8000 m | 1000 m | 1000 m | 3500 m | 300 m |
| | FREQUENCY BAND | | 48 - 78 kHz | 42 - 65 kHz | 18 - 34 kHz | 18 - 34 kHz | 15 - 27 kHz | 13 - 24 kHz | 7 - 17 kHz | 7 - 17 kHz | 7 - 17 kHz | 48 - 78 kHz | 42 - 65 kHz | 18 - 34 kHz | 120 - 180 kHz |
| | TRANSDUCER BEAM PATTERN | | horizontally omnidirectional | wide - angle 100 degrees | horizontally omnidirectional | hemispherical | wide-angle 120 degrees | directional 70 degrees | hemispherical | directional 80 degrees | hemispherical | horizontally omnidirectional | wide - angle 100 degrees | horizontally omnidirectional | omnidirectional |
| - | ACOUSTIC CONNECTION | | up to 31.2 kbit/s | up to 31.2 kbit/s | up to 13.9 kbit/s | up to 13.9 kbit/s | up to 9.2 kbit/s | up to 9.2 kbit/s | up to 6.9 kbit/s | up to 6.9 kbit/s | up to 6.9 kbit/s | up to 31.2 kbit/s | up to 31.2 kbit/s | up to 13.9 kbit/s | up to 62.5 kbit/s |
| LION | BIT ERROR RATE | | less than 10 ⁻¹⁰ | | | | | | less than 10 ⁻¹⁰ | | | less than 10 ⁻¹⁰ | | | |
| NEC. | INTERNAL DATA BUFFER 1 MB, configurable | | | | | | 1 MB, configurable | | | 1 MB, configurable | | | | | |
| NO | INTERFACE ^{1]} Ethernet or RS-232 | | | | | | Ethernet or RS-232 | | | Ethernet or RS-232 | | | | | |
| 0 | INTERFACE CONNECTORS up to 4 connectors, Ethernet and serial combinations | | | | | | up to 4 connec | ctors, Ethernet and ser | al combinations | 1 connector | | | | | |
| | POWER CONSUMPTION ²⁾ | Stand-by Mode | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 2.5 mW | 0.5 mW |
| POWER | | Listen Mode | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | 5 - 285 mW | | not av | ailable | |
| | | Receive Mode | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W | 0.8 W |
| | | Transmit Mode | up to 60 W | up to 40 W | up to 65 W | up to 65 W | up to 65 W | up to 57 W | up to 45 W | up to 65 W | up to 70 W | up to 55 W | up to 35 W | up to 55 W | up to 8.5 W |
| | POWER SUPPLY OPTIONS 3) | External | 24 VDC (12 VDC) | | | | | | 24 VDC (12 VDC) | | | 24 VDC (12 VDC) | | | |
| | Internal Rechargeable battery 5 Ah or 10 Ah | | | | | | Rechargeable battery 5 Ah or 10 Ah | | | Rechargeable battery 3.350 Ah | | | | | |
| | HOUSING OPTIONS | Delrin | Plastic non-magnetic corrosion-resistant housing for short-term deployments, depth rating 200 m | | | | | | \checkmark | \checkmark | \checkmark | \checkmark \checkmark \checkmark | | | |
| | | | Light metal housing for short-term deployments, depth rating 2000 m | | | | | \checkmark | \checkmark | \checkmark | not available | | | | |
| Ļ | | Stainless Steel | Robust metal, suitable for long-term deployments in harsh environments, depth rating 1000 m or 2000 m | | | | | | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark |
| SICA | Titanium Corrosion resistant housing, suitable for long-term deployment in harsh environments, depth rating 6000 m | | | | | | | ng 6000 m | \checkmark | \checkmark | \checkmark | not available | | | |
| ΛH | DIMENSIONS ⁴ | Housing Total length | Ø 110 x 178 mm 265 mm | Ø 110 x 178 mm 265 mm | Ø 110 x 178 mm 265 mm | Ø 110 x218 mm 300 mm | Ø 110 x 178 mm 295 mm | Ø 113 x 220 mm 390 mm | Ø 110 x 178 mm 322 mm | Ø 110 x 178 mm 338 mm | Ø 110 x 178 mm 246 mm | Ø 63 mm x 235 mm 310 mm | Ø 63 mm x 235 mm 300 mm | Ø 63 mm x 235 mm 310 mm | Ø 63 mm x 235 mm 310 mm |
| | WEIGHT, dry/wet | Delrin | 2250/400 g | 2300/300 g | 2245/400 g | 3100/1200 TBC g | 3850/1080 g | 2990/490 g | 4700/600 g | 6200/600 g | 3000/490 g | 1120/330 g | 1210/420 g | 1265/480 g | 1120/330 g |
| | WAKE-UP MODULE ⁵) not compatible with Ethernet The Wake Up Module turns the rest of the device on if it detects incoming acoustic signals or incoming data on one host interface. Once the device completes receiving or transmitting data, it switches itself off. 2-connector version available for R-series | | | | | | ta on one host inter- vailable for R-series | \checkmark | \checkmark | \checkmark | ✓ single-interface version only | | | | |
| D OPTIONS | POWER SWITCH ⁶) not compatible with Ethernet The Power Switch allows to provide power supply to up to 4 external instrumer | | | | | | s and turn them on/o | off on command | \checkmark | \checkmark | \checkmark | | not av | vailable | |
| | ADVANCED TIMEKEEPING MODUL | E | Allows to accept 1 PPS input from GPS, optionally includes a Chip Scale Atomic Clock for highly precise timekeeping | | | | | | \checkmark | \checkmark | \checkmark | \checkmark only available for OEM modem versions | | | |
| | SDM VERSION | | Software Defined Modem mode: transmit/receive arbitrary waveforms and set a reference to trigger signal detection | | | | | | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark |
| AN | ACOUSTIC RELEASE DEVICE Baseline transponders - reliable mechanism for recovery to the surface. Also available in OEM version for system integration | | | | | | \checkmark | \checkmark | \checkmark | not available | | | | | |
| ULES | FLOATATION COLLAR | | Baseline transponders - floatation collar for fast recovery to the surface | | | | | \checkmark | \checkmark | \checkmark | not available | | | | |
| IODI | PRESSURE SENSOR | | Accurate pressure measurements | | | | | | \checkmark | \checkmark | \checkmark | not available | | | |
| 2 | CABLE - MOUNTED TRANSDUCER | Separated transducer for easier system integration. Standard cable length 1.5 m, other upon request. | | | | | | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | |
| | OEM VERSION | | Version without housing: transducer and electronics for system integration | | | | | | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark | \checkmark |
| APPLICATIONS | | | Fast short and medium range transmissions in | Fast short and medium range transmis- sions in vertical, slant and | Medium range transmissions in | Medium range transmissions in | Long range transmissions in vertical and slant channels, | Long range transmissions in vertical and slant channels, | Long range transmissions ir vertical and slant channels, | Long range transmissions in vertical | Long range transmissions in slant | Fast short and medium range communication | Fast short and medium range communication | Medium range communi- cation for UUVs | High-speed short range communication for UUVs |

¹⁾ One RS-232 Interface can be replaced with a RS-422 interface. Contact Evologics for more information!

2) Power consumption for RS-232 interface. Add 500 mW if an Ethernet interface is installed. Add 300 mW if the Wake-Up Module is installed. User-configurable Listen Mode is only available with a Wake-Up module installed. Power consumption in Listen Mode depends on Listen Mode settings.

³⁾ 300 VDC available for 42/65 models. Contact Evologics for more information on external and internal power supply options!

⁴¹ Dimensions of a build in Delrin housing, other builds are slightly larger. Dimensions vary depending on housing type and installed options. Contact Evologics for more information on device dimensions and weights, request a drawing if necessary.

³ The Wake Up Module is only compatible with RS-232 interface! It is not compatible with Ethernet or RS-422. 2-channel Wake Up Module version reacts to incoming data on two serial interfaces.

⁶⁾ The Power Switch is only compatible with RS-232 interface! It is not compatible with Ethernet or RS-422.



OEM ACOUSTIC RELEASE DEVICE



ABOUT US

Evologics GmbH develops underwater information and communication systems based on bionic concepts, combining cutting edge engineering with the best ideas found in nature. The advanced product features have become enabling technologies for deep water exploration and production.

Evologics range of products offers highly reliable, flexible and cost-effective solutions for multiple underwater communication, positioning, navigation and monitoring applications. We strive for innovation and invest our vast experience into developing, manufacturing and supporting products that deliver an excellent performance and solve the most challenging tasks.

The company was founded in 2000 in Berlin, Germany, by a group of leading international scientists and maritime engineering experts. The company since focuses on developing innovative solutions for maritime and offshore industries, as well as smart robotic systems design and bionic research.

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EUROPÄISCHE UNION Europäischer Fonds für regionale Entwicklung Investition in Ihre Zukunft

