

LumiCam 2400B Series

2D Imaging Colorimeter

Key features at a glance

- Motorized objective lenses
- Up to 30 % shorter measurement time due to optimized stepper motor actuation
- Approx. 20 % smaller footprint for compact design
- ▲ Various analysis features such as spotmeter, polygons, and flexible polylines
- Straightforward determination of luminance distributions, color coordinates / temperature, Planck distance, dominant wavelength, or contrast



**** TECHNICAL SPECIFICATIONS

LumiCam 2400B	Mono	Color	Advanced	
Quantities				
Photometric quantities	Luminance (cd/m ²), luminous intensity (cd), contrast			
Colorimetric quantities	-	Color coordinates (x,y), color coordinates (u',v'), tristimulus values (X, Y, Z), dominant wavelength (nm), color saturation, correlated color temperature CCT (K)		
Camera data				
Sensor	Sony IMX264LLR CMOS Sensor			
Sensor size	2/3", 11.1 mm diagonal			
Effective number of pixels (h x v)	2428 x 2028 (5 MP)			
Pixel size	3.45 μm x 3.45 μm			
AD converter	12 bit			
Exposure time	40 µs to 30 s			
Luminance measurement				
Measurement range 1)	0.3 mcd/m ² – 2.5 Mcd/m ²			
Extended measurement range 2)	2.5 x 10 ¹⁰ cd/m ²			
Measurement time incl. data saving time (at 10 cd/m ²) $^{3)}$	1.9 s			
Measurement time incl. data saving time (at 100 cd/m ²) $^{3)}$	1.8 s			
Accuracy for std. illuminant A 4)	±3 %	±3 %	±3 %	
Accuracy for LED color light ⁸⁾	-	-	±2 %	
Repeatability ⁵⁾	±0.03 %			
Linearity	±0.5 %			
Uniformity ⁶⁾	±0.5 %			
Filter match 7)	f ₁ ' < 3 %			



**** TECHNICAL SPECIFICATIONS

Color measurement				
Measurement time incl. data saving time (at 10 cd/m ²) $^{3)}$	-	10 s	16 s	
Measurement time incl. data saving time (at 100 cd/m ²) $^{3)}$	-	8 s	12 s	
Accuracy (x, y) for std. illuminant A 4)	-	±0.003	±0.003	
Accuracy (x, y) for color light ⁸⁾	-	±0.010	±0.010	
Accuracy (x, y) for LED color light 9)	-	-	±0.005	
Repeatability (x, y) ⁵⁾	-	±0.0001	±0.0003	
Uniformity (x, y) ⁶⁾	-	±0.001	±0.001	
Filter match	f1' (Y) < 3 %	$\begin{array}{l} f_{1}{}^{*}\left(Xb\right) < 6 \ \% \\ f_{1}{}^{*}\left(Xr\right) < 6 \ \% \\ f_{1}{}^{*}\left(Y\right) < 3 \ \% \\ f_{1}{}^{*}\left(Z\right) < 4 \ \% \end{array}$	$\begin{array}{l} f_{1}{}^{\prime}\left(Xb\right) < 6 \ \% \\ f_{1}{}^{\prime}\left(Xr\right) < 6 \ \% \\ f_{1}{}^{\prime}\left(Y\right) < 3 \ \% \\ f_{1}{}^{\prime}\left(Z\right) < 4 \ \% \end{array}$	
General				
Interface	Gigabit Ethernet			
Operating system	Windows 7 (32/64 bit), Windows 10 (64 bit)			
Dimensions (L x W x H) (incl. 50 mm objective lens, no handle)	210 mm x 105 mm x 100 mm	235 mm x 119 mm x 133 mm		
Weight	1.5 kg	3 kg		
Power supply	24 V external			
Operating conditions	10 to 40 °C, max. 70 % relative humidity (non-condensing)			

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¹⁾ The lower limit corresponds to the maximal exposure time and smallest f-number at SNR 10:1 and vice versa.

²⁾ Valid for OD4 filter.

³⁾ Value calculated from 100 repetitions taking data saving time into account.

⁴⁾ Calculated from 100 repetitions; refers to the deviation of the mean from the reference value.

⁵⁾ Calculated from 50 repetitions. Refers to the double standard deviation of the measured values.

⁶⁾ Refers to the maximum deviation from the mean value calculated from flat-field verification image.

 $^{\eta}\,$ Deviation of the filter transmission from the V(\lambda) curve integrated over the entire visible spectrum.

Maximum deviation from the reference source (illuminant A with set of color glass filters).
Derived from 20 repetitions for R, G, and B - LEDs with optimized signal level. Refers to the double standard deviation.